1.4

Tijd onderdeel: 30:43

|  |  |
| --- | --- |
| Pulse | **def** pulse(pin, delay1, delay2):  GPIO.output(pin, GPIO.HIGH)  time.sleep(delay1)  GPIO.output(pin, GPIO.LOW)  time.sleep(delay2)  *# copieer hier je implementatie van de pulse functie* **def** servo\_pulse(pin\_nr, position):  x = (position \* 0.00002) + 0.0005  y = 0.02 - x  pulse(pin\_nr, x, y) |
| Blink | **while True**:  **for** i **in** range(0, 100, 1):  servo\_pulse(servo, i)  time.sleep(0.48)  **for** i **in** range(100, 0, -1):  servo\_pulse(servo, i)  time.sleep(0.48) |